



Operating Instructions  
thermoMETER UC

UC-SF02-Sx  
UC-SF15-Sx  
UC-SF22-Sx

Infrared sensor

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# 1 Safety

## 1.1 Symbols used

System operation assumes knowledge of the operating instructions.

The following symbols are used in these operating instructions:

 CAUTION	Indicates a hazardous situation which, if not avoided, may result in minor or moderate injury.
 NOTICE	Indicates a situation that may result in property damage if not avoided.
►	Indicates a user action.
 i	Indicates a tip for users.
Measurement	Indicates hardware or a software button/menu.

## 1.2 Warnings

 CAUTION	Connect the power supply and the display/output device according to the safety regulations for electrical equipment.
	<ul style="list-style-type: none"> <li>• Risk of injury</li> <li>• Damage to or destruction of the sensor</li> </ul>
 NOTICE	The supply voltage must not exceed the specified limits.
	<ul style="list-style-type: none"> <li>• Damage to or destruction of the sensor</li> </ul>
	Avoid knocks and impacts to the sensor.
	<ul style="list-style-type: none"> <li>• Damage to or destruction of the sensor</li> </ul>
	Protect the sensor cable against damage.
	<ul style="list-style-type: none"> <li>• Destruction of the sensor</li> <li>• Failure of the measuring device</li> </ul>
	Never fold the sensor cable and do not bend it in tight radii.
	The minimum bending radius is 22 mm (static). Dynamic movement is not permitted.
	<ul style="list-style-type: none"> <li>• Damage to or destruction of the sensor cable</li> <li>• Failure of the measuring device</li> </ul>
	Avoid exposure of sensor (both optics and housing) to cleaning agents that contain solvents.
	<ul style="list-style-type: none"> <li>• Damage to or destruction of the sensor</li> </ul>
	Avoid abrupt changes in ambient temperature.
	<ul style="list-style-type: none"> <li>• Inaccurate or incorrect measurements</li> </ul>

## 1.3 Notes on product marking

### 1.3.1 CE marking

The following apply to the product:

- Directive 2014/30/EU ("EMC")
- Directive 2014/35/EU ("Low Voltage")
- Directive 2011/65/EU ("RoHS")

Products which carry the CE marking satisfy the requirements of the EU Directives cited and the relevant applicable harmonized European standards (EN).

The product is designed for use in industrial and laboratory environments.

The EU Declaration of Conformity and the technical documentation are available to the responsible authorities according to the EU Directives.

### 1.3.2 UKCA marking

The following apply to the product:

- SI 2016 No. 1091 ("EMC")
- SI 2016 No. 1101 ("Low Voltage")
- SI 2012 No. 3032 ("RoHS")

Products which carry the UKCA marking satisfy the requirements of the directives cited and the relevant applicable harmonized standards.

The product is designed for use in industrial and laboratory environments.

The UKCA Declaration of Conformity and the technical documentation are available to the responsible authorities according to the UKCA Directives.

### 1.4 Intended use

The system is designed for use in industrial and laboratory applications.

It is used for non-contact temperature measurement.

The system must only be operated within the limits specified in the technical data, [see Chap. 2.3](#).

Take additional precautions for safety and damage prevention in case of safety-related applications.

### 1.5 Proper environment

Temperature range:	Sensor:	Storage:	-40 ... 85 °C
	Operation:	UC-SF02:	-20 ... 120 °C
		UC-SF15:	-20 ... 180 °C
		UC-SF22:	
	Controller:	Storage:	-40 ... 85 °C
	Operation:		-20 ... 80 °C
Humidity:			10 % RH ... 95 % RH (non-condensing)
		Controller:	IP65
		Sensor:	IP65

#### NOTICE

Avoid rapid changes in the ambient temperature of the sensor.

- Inaccurate measurement values

## 2 Functional principle, technical data

### 2.1 Functional principle

The sensors are non-contact infrared temperature measurement sensors. They measure the infrared radiation emitted by objects and calculate the surface temperature based on this.

The sensor housing is made of stainless steel (protection class IP65). The controller is housed in a separate die-cast aluminum housing.

i The sensors are sensitive optical systems. They should therefore only be fitted using the existing thread.

#### NOTICE

Avoid rough mechanical force on the sensor.

- Destruction of the sensor

### 2.2 Sensor models

The sensors are available in the following versions:

Series	Model	Measuring range	Spectral range	Output	Optics
UC-SF02	UC-SF02-S1	-50 to 600 °C	8 to 14 µm	0 (4) ... 20 mA / 0 ... 5 V / 0 ... 10 V (freely scalable within the measuring range)	2:1
	UC-SF02-S3				
	UC-SF02-S8				
	UC-SF02-S15				
UC-SF15	UC-SF15-S1	-50 to 600 °C	8 to 14 µm	0 (4) ... 20 mA / 0 ... 5 V / 0 ... 10 V (freely scalable within the measuring range)	15:1
	UC-SF15-S3				
	UC-SF15-S8				
	UC-SF15-S15				
UC-SF22	UC-SF22-S1	-50 to 900 °C (1000 °C)	8 to 14 µm	0 (4) ... 20 mA / 0 ... 5 V / 0 ... 10 V (freely scalable within the measuring range)	22:1
	UC-SF22-S3				
	UC-SF22-S8				
	UC-SF22-S15				

Tab. 2.1: Sensor models

### 2.3 Technical data

Model	UC-SF02	UC-SF15	UC-SF22
Optical resolution	2:1	15:1	22:1
Measuring range <sup>[1]</sup>	-50 to 600 °C	-50 to 600 °C	-50 to 900 °C (1000 °C)
Spectral range	8 to 14 µm	8 to 14 µm	8 to 14 µm
System accuracy <sup>[2]</sup>		±1.0 % or ±1.0 °C	
Repeatability <sup>[2]</sup>		±0.5 % or ±0.5 °C	
Temperature resolution (NETD) <sup>[3]</sup>		50 mK	
Response time <sup>[4]</sup>	20 ms		120 ms
Emissivity		0.100 to 1.100	
Transmittance		0.100 to 1.100	

[1] Measuring range can optionally be extended to 1000 °C (only SF22)

[2] Valid for object temperatures >0 °C and for an ambient temperature of 24 °C ±2 °C; the greater value applies ( $\varepsilon=1$ )

[3] With a time constant of 200 ms and an object temperature of 200 °C

[4] 0 - 90 % energy; adjustable via software

Model	UC-SF02	UC-SF15	UC-SF22
Signal processing	Intelligent averaging, Min/Max, Hold function with threshold/hysteresis (adjustable via software and buttons)		
Supply voltage	5 ... 36 VDC		
Max. current consumption	< 150 mA		
Digital interface <sup>[5]</sup>	RS485 / USB (3.3V-LVTTL) / Ethernet / EtherCAT / PROFINET / EtherNet/IP		
Analog output <sup>[6]</sup>	0 (4) ... 20 mA / 0 ... 5 V / 0 ... 10 V (freely scalable within the measuring range)		
Switching output	2x relays for alarm (min/max); 400 mA (short-circuit proof)		
Connection	Sensor	Integrated cable, standard length 3 m, optional 1 m, 8 m or 15 m possible	
	Controller <sup>[7]</sup>	Supply/digital and relay output: 8-pin M12 plug connector (socket) Supply/analog output: 5-pin M12 plug connector (plug)	
Mounting	Sensor	Direct fastening via integrated M12x1 thread or fastening using the hexagon nut included in the scope of delivery	
Temperature range	Sensor	Storage	-40 ... 85 °C
		Operation	-20 ... 120 °C
	Controller	Storage	-40 ... 85 °C
		Operation	-20 ... 80 °C
Humidity	10 % RH ... 95 % RH (non-condensing)		
Shock (DIN EN 60068-2-27)	50g, 11 ms, each axis		
Vibration (DIN EN 60068-2-6)	3g / 11 ... 200 Hz, each axis		
Protection class (DIN EN 60529)	Sensor	IP65	
	Controller	IP65	
Material	Sensor	Stainless steel (1.4404)	
	Controller	Aluminum die-cast	
Weight	Sensor	approx. 20 g	
	Controller	approx. 280 g	
Control and indicator elements <sup>[8]</sup>	LCD display & membrane keypad for button operation optional operation via sensorTOOL		

i

With all UC sensor models, the sensor cable must not be moved during the measurement.

[5] Connection via an interface module is required for Ethernet, EtherCAT, PROFINET and EtherNet/IP, USB interface only via USB cable (see accessories)

[6] Depends on supply voltage

[7] The supply via the optional USB cable (VCC = 5 V) and the supply up to 36 V can be connected at the same time; the higher voltage supply is used in each case. When operating without a USB cable, the power supply up to 36 V can be connected to one of the two M12s.

[8] Access with sensorTOOL requires USB adapter (see accessories)

### 3 Delivery

#### 3.1 Unpacking, included in delivery

- 1 Sensor with sensor cable and protective cap
- 1 Controller
- 1 Mounting nut (M12x1)
- 1 Setup guide

► Carefully remove the components of the measuring system from the packaging and ensure that the goods are forwarded in such a way that no damage can occur.

► Check the delivery for completeness and shipping damage immediately after unpacking.

► If there is damage or parts are missing, immediately contact the manufacturer or supplier.

Optional accessories are listed in the appendix.

#### Return of packaging

Micro-Epsilon Messtechnik GmbH & Co. KG offers customers the opportunity to return the packaging of products purchased from Micro-Epsilon by prior arrangement so that it can be reused or recycled.

To arrange the return of packaging, for questions about the costs and / or the exact return procedure, please contact us directly at

info@micro-epsilon.de

#### 3.2 Storage

Temperature range: -40 ... 85 °C

Humidity: 10 % RH ... 95 % RH (non-condensing)

## 4 Optical tables

### 4.1 Description optical tables

The following optical tables show the diameter of the measurement spot dependent on the measurement distance. The measurement spot size refers to 90% of the radiation energy. The distance is measured from the front edge of the sensor / CF lens.

i The size of the object to be measured and the optical resolution of the IR thermometer determine the maximum distance between sensor and object. To avoid measuring errors, the measuring object should completely fill the field of vision of the sensor's optical system. This means, the measurement spot must always be at least as large as or smaller than the measuring object.

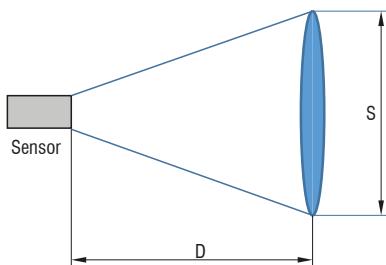


Fig. 4.1: Optical diagram

D = Distance

S = Spot size

### 4.2 Optical specifications

Standard Focus (in mm)											
SF02	2:1	7	53.8	102.5	151.3	200	251.3	302.5	353.8	405	
Distance		0	100	200	300	400	500	600	700	800	
SF15	15:1	7	11.5	14	18	23.5	29.5	35.5			
Distance		0	100	200	300	400	500	600			
SF22	22:1	7	14	12	18.5	23	28	33	36.5	38.5	40
Distance		0	60	110	210	310	410	510	610	710	810
											910

Close Focus (when using the screwable CF lens, in mm)								
CF02	2:1	6.5	3.9	2.8	2.5	4.8	6.4	8
Distance		0	10	20	25	30	35	40
CF15	15:1	6.5	3.7	0.8	4.1	5	6.8	8.8
CF22	22:1	6.5	3.4	0.6	4	4.5	6.2	8
Distance		0	5	10	15	20	25	30

= smallest spot size / focal point (mm)

The ratio D:S (example 2:1, see table) describes the ratio Distance (distance from the front edge of the sensor to the measuring object) to Spot size (measurement spot size).

## 5 Installation and assembly

### 5.1 Mechanical installation

#### 5.1.1 Sensor and controller

The sensors have a metric M12x1-thread and can be attached to available mounting equipment either directly via this sensor thread or by means of the nut included.

Various mounting brackets and fixtures are available as accessories to facilitate the alignment of the sensor with the object.

- i Mount the sensor via the provided thread.

#### NOTICE

Avoid rough mechanical force on the sensor.

- Destruction of the sensor

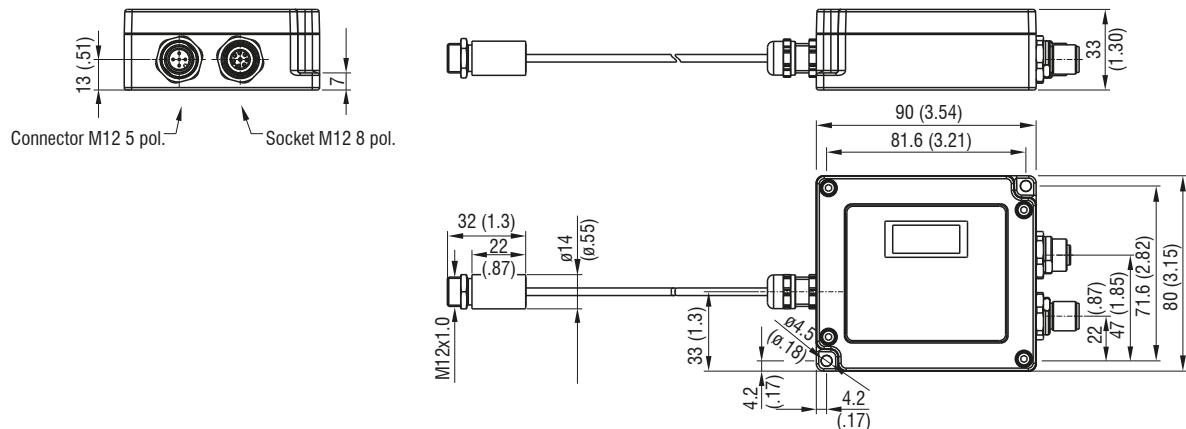


Fig. 5.1: thermoMETER UC, dimensions in mm (inches, rounded off)

#### 5.1.2 Sensor cable

The sensor is supplied with a ready-made sensor cable <sup>[9]</sup>

If the sensor cable is defective, see Chap. 13.

- i Never bend the sensor cable more tightly than the bending radius.  
The minimum bending radius is 22 mm.

#### NOTICE

The sensor cable must not be shortened under any circumstances.

- Inaccurate or incorrect measurements

- i With all UC sensor models, the sensor cable must not be moved during the measurement.

### 5.2 Electrical installation

#### 5.2.1 Connection possibilities

[9] The standard length of the sensor cable is 3 m. Optional lengths of 1 m, 8 m or 15 m are possible.

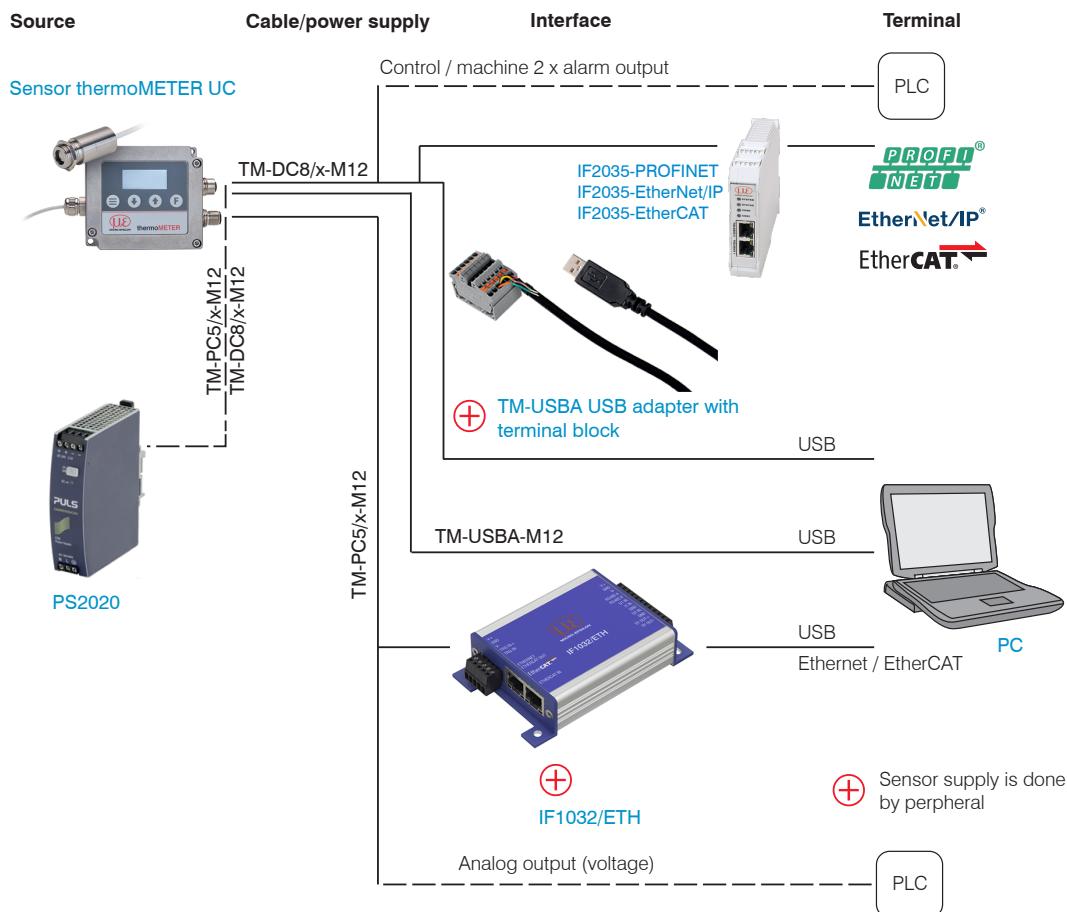
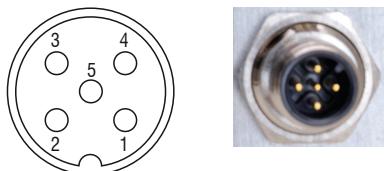


Fig. 5.2: Connection options thermoMETER UC

### 5.2.2 Pin assignment

Pin	Wire color 5-pin M12 analog cable	Signal
1	Brown	VCC
2	White	I_OUT
3	Blue	GND
4	Black	U_OUT
5	Gray	Laser (3.3 V)

Tab. 5.1: Pin assignment analog connection 5-pin M12 connector

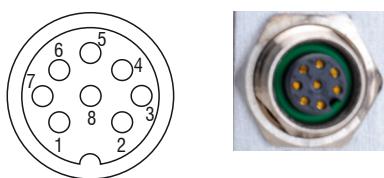


Tab. 5.2: Analog connection, view: 5-pin M12 connector on the controller

Micro-Epsilon recommends using the 5-pin M12 analog cable from the optional accessories.

Pin	Wire color 8-pin M12 digital cable	Signal
1	White	Relay 1
2	Brown	VCC/USB (5 V)
3	Green	RX
4	Yellow	TX
5	Gray	D+ (RS485)
6	Pink	D- (RS485)
7	Blue	GND
8	Red	Relay 2
Housing	Shield	

Tab. 5.3: Pin assignment digital connection 8-pin M12 socket



Tab. 5.4: Digital connection, view: 8-pin M12 socket on the controller

Micro-Epsilon recommends using the 8-pin M12 digital cable from the optional accessories.

### 5.2.3 Power supply

Use a power supply unit with an output voltage of 5 ... 36 VDC, which supplies a current of at least 200 mA. Residual ripple should be no more than 200 mV (peak/peak).

#### NOTICE

Never apply voltage to the analog outputs.

- Destruction of the output

The sensor is not a two-wire sensor!

### 5.2.4 Plug-in connections

For the plug-in connections, you can choose either the analog version with one cable or the digital version with one or both cables as follows:

- Connect a 5-pin M12 analog cable <sup>[10]</sup> to the 5-pin M12 connector on the controller.
- Connect an 8-pin M12 digital cable <sup>[10]</sup> to the 8-pin M12 socket on the controller.

[10] Micro-Epsilon recommends using the 5-pin M12 analog cable or the 8-pin M12 digital cable from the optional accessories.

## 6 Outputs

### 6.1 Overview

The sensor has one analog output channel and two alarm outputs.

#### NOTICE

- Never apply voltage to the analog output.
- Destruction of the output

Available outputs	
Analog output	Voltage
	Current
Alarm output	Alarm output 1
	Alarm output 2

Tab. 6.1: Overview of outputs

### 6.2 Analog output

The analog output is used to output the object temperature. The output signal is selected using the programming buttons or the **sensorTOOL**. Both alarm outputs can also be programmed at the same time.

Analog output	Range
Voltage	0 ... 5 V
	0 ... 10 V
Current	0 ... 20 mA
	4 ... 20 mA

Tab. 6.2: Overview of analog outputs

The output values in the value range are freely selectable.

### 6.3 Alarm outputs

The sensor features the following alarm functions:

- Alarm output 1 with relay; preconfigured as minimum alarm
- Alarm output 2 with relay; preconfigured as maximum alarm

The alarm limits and the alarm configuration can be changed using the programming buttons or the **sensorTOOL**.

## 7 Operation via programming keys

### 7.1 Start the measurement

After the sensor is connected to the supply voltage, the sensor starts an initialization routine and shows the current firmware version on the display for a few seconds. The temperature of the measured object then appears. The color of the display lighting changes depending on the alarm settings.

### 7.2 Sensor settings

You can operate and configure the sensor using the 4 programming keys.

Key	Explanation
	This key is used to switch between the menu and the measurement chart.
	Switch through the menus or change the parameters in a menu.
	Switch through the menus or change the parameters in a menu.
	Select and confirm the entry or function

Tab. 7.1: Meaning of the programming keys

There are 9 different function parameters available for setting the sensor and the measurement, [see Chap. 7.4](#).

The calculated temperature of the measured object is displayed if none of the keys are pressed for longer than  $\geq 30$  seconds. This is based on the settings that were previously selected.



Fig. 7.1: Display and programming keys

### 7.3 Reset to factory settings

Go to the menu **System > FactRes. > Apply** to reset all settings to the factory settings.

## 7.4 Function parameters

Display	Selection	Fine selection	Value range (adjustable)	Explanation
Infrared	Epsilon		[0.1 - 1.1]	Setting the emissivity. The emissivity ( $\epsilon$ - epsilon) is a material constant that describes the ability of a body to emit infrared energy.
	Transm.		[0.1 - 1.1]	Setting the transmittance. If a protective window or additional lens is mounted between the sensor and the measuring object, the resulting signal loss can be compensated for with this entry.
	Amb. Head	Off		The ambient temperature of the sensor can falsify the measurement result. This influence can be reduced/minimized by activating compensation. The following options are available: OFF, Auto and Fixed:  Off: No compensation
		Auto		Auto: The internal head temperature measurement is used for compensation.
		Fixed / Fixed AH	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	Fixed: A fixed ambient temperature is used for the compensation calculation.
Average	Avg. Time		[0.10 - 999.95s]	This entry defines the time constant for averaging. The signal is smoothed using an arithmetic algorithm.
	Avg. Mode			Depending on the selection, an arithmetic mean value is calculated with the separately set time constant.
			Normal	Arithmetic averaging
			Smart	Intelligent averaging: Fast temperature increases are passed directly to the signal output and fast, dynamic events can be recorded despite averaging
Holdmode	Off			Off deactivates the extended signal processing functions. The advanced functions are activated via the other entries.
	Peak	H.P. Time	[0.1 - 999.9s]	The Peak Hold function is used to search for the maximum value. The respective signal maximum is held for the set time. After the hold time has elapsed, the signal drops to the second highest value or decreases by 1/8 of the difference between the previous maximum value and the minimum value during the hold time. This value is in turn held for the set time. The signal then falls with a slow time constant and follows the course of the object temperature.
	Valley	H.P. Time	[0.1 - 999.9s]	Valley Hold is used to search for the minimum value. The respective signal minimum is held for the set time. This algorithm is the inverse of that for the maximum search.
	A. Peak	Tresh.	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	In the extended maximum search, this algorithm searches for local maximum values. Maximum values that are lower than their predecessors are only accepted if the temperature had previously fallen below the threshold value. If hysteresis is set, a maximum value must also have dropped by the hysteresis value before it is accepted as the new maximum.
		Hyst.	[0.0 - 600°C]	
	A. Valle	Tresh.	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	In the extended minimum search, this algorithm searches for local minimum values. Minimum values that are greater than their predecessors are only accepted if the temperature previously exceeded the threshold value. If hysteresis is set, a minimum value must also have risen by the value of the hysteresis before it is accepted as the new minimum.
		Hyst.	[-50 - 900°C] [0.0 - 600°C]	

Display	Selection	Fine selection	Value range (adjustable)	Explanation
Output	Disabled			The <b>Disabled</b> setting deactivates all analog outputs.
	Voltage	0-T.min	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	Setting the upper and lower temperature limit for scaling the analog output.
		0-T.max	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	
		0-V.min	[0 - 10V]	Setting the upper and lower limit for the output scaling of the voltage output.
		0-V.max	[0 - 10V]	
	Current	0-T.min	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	Setting the upper and lower temperature limit for scaling the analog output.
		0-T.max	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	
		0-mA.min	[0 - 20mA]	Setting the upper and lower limit for the output scaling of the current output.
		0-mA.max	[0 - 20mA]	
Alarm 1	Alarm 1	Off		Off deactivates alarm output 1. The other entries are used to define the alarm source for alarm output 1. The temperature determines when the alarm is triggered and the alarm relay 1 changes its switching state.
		TProces	[-50 - 600°C] SF02 / SF15 or [-50 - 900°C] SF22	Setting the temperature and the alarm source [TProces] Process temperature = temperature value with signal processing functions
		TAverag		Setting the temperature and the alarm source [TAverag] Averaged temperature = temperature value with averaging function
		TActual		Setting the temperature and the alarm source [TActual] Raw temperature value = temperature value without signal processing functions
		TBox		Setting the temperature and the alarm source Controller temperature
		THead		Setting the temperature and the alarm source Sensor head temperature
		Diffmod		Setting the temperature and the alarm source Differential temperature between TActual - THead

Display	Selection	Fine selection	Value range (adjustable)	Explanation
Alarm 2	Alarm 2	Off		Off deactivates alarm output 2. The other entries are used to define the alarm source for alarm output 2. The temperature determines when the alarm is triggered and the alarm relay 2 changes its switching state.
		TProces	[-50 - 600 °C] SF02 / SF15 or [-50 - 900 °C] SF22	Setting the temperature and the alarm source [TProces] Process temperature = temperature value with signal processing functions
		TAverag		Setting the temperature and the alarm source TAverag Averaged temperature = temperature value with averaging function
		TActual		Setting the temperature and the alarm source [TActual] Raw temperature value = temperature value without signal processing functions
		TBox		Setting the temperature and the alarm source Controller temperature
		THead		Setting the temperature and the alarm source Sensor head temperature
		Diffmod		Setting the temperature and the alarm source Differential temperature between TActual - THead
Aiming	Off			No alignment aid
	Valley			Optical alignment aid via the LCD backlight to find the position with the lowest temperature
	Peak			Optical alignment aid via the LCD backlight to find the position with the highest temperature
	Laser	ON / OFF		Activation of the power supply for an optional laser sighting

Display	Selection	Fine selection	Value range (adjustable)	Explanation
Display	Row 1	TProces		Selection for displaying the temperature TProces for the first display line [TProces] Process temperature = temperature value with signal processing functions
		TAverag		Selection for displaying the temperature TAverag for the first display line [TAverage] Averaged temperature = temperature value with averaging function
		TActual		Selection for displaying the temperature TActual for the first display line [TCurrent] Raw temperature value = temperature value without signal processing functions
		TBox		Selection for displaying the electronics box temperature TBox for the first display line
		THead		Selection for displaying the sensor head temperature THead for the first display line
		Epsilon		Selection for displaying the value Epsilon for the first display line on Thead
	Row 2	TProces		Selection for displaying the temperature TProces for the second display line [TProces] Process temperature = temperature value with signal processing functions
		TAverag		Selection for displaying the temperature TAverag for the second display line [TAverage] Averaged temperature = temperature value with averaging function
		TActual		Selection for displaying the temperature TActual for the second display line [TCurrent] Raw temperature value = temperature value without signal processing functions
		TBox		Selection for displaying the electronics box temperature TBox for the second display line
		THead		Selection for displaying the sensor head temperature THead for the second display line
		Epsilon		Selection for displaying the value Epsilon for the second display line on Thead
	AutoOFF	perm.on		Deactivation of the automatic switch-off of the display backlight.
		1 min ... 10 min		Activation of automatic switch-off of the display backlight after 1 ... 10 minutes.

Display	Selection	Fine selection	Value range (adjustable)	Explanation
System	FactRes.	Apply		This entry is used to reset the sensor to the factory parameters.
		No		There is no action.
	Baud rate	9600		Setting the baud rate for digital communication with the sensor to 9600
		19200		Setting the baud rate for digital communication with the sensor to 19200
		38400		Setting the baud rate for digital communication with the sensor to 38400
		57600		Setting the baud rate for digital communication with the sensor to 57600 baud
		115200		Setting the baud rate for digital communication with the sensor to 115200 baud
	T. Unit	°C / °F	[ °C / °F ]	Setting the temperature unit for the display and data output. You can choose between °C and °F.
	485 Term	ON/OFF	[ON/OFF]	Activation or deactivation of the integrated 120 Ohm terminating resistor of the RS485 interface
	485 Adr.		1 - 126	Setting the RS485 bus address via which the sensor can be addressed on an RS485 bus. The preset bus address is 126, which is the usual standard address for Micro-Epsilon sensors.
	Protocol	ME bus		This entry is used to switch digital communication to the <b>ME-Bus</b> protocol. It enables the digital readout and setting of all sensor functions conveniently with the Micro-Epsilon sensorTOOL.
		Binary		This entry is used to switch digital communication to the simplified binary protocol. This protocol enables the digital setting of a limited selection of sensor functions.

Tab. 7.2: Menu structure

## 8 Operation via sensorTOOL software

### 8.1 Description

sensorTOOL by Micro-Epsilon is software that you can use to apply settings to the sensor and to view and document measurement data.

- ▶ Connect the sensor to the USB interface of a PC/notebook using the optionally available 8-pin M12 digital cable with USB plug or:
- ▶ Connect the sensor to the USB interface of a PC/notebook using the optionally available 8-pin M12 digital cable in combination with the USB adapter with terminal block.

The supply voltage is supplied via the USB interface.

- ▶ Before using the USB adapter for the first time, install the corresponding driver TM-USBA-adapter-driver. You can find the current driver at <https://www.micro-epsilon.com/fileadmin/download/software/tm-usba-adapter-driver.zip>.
- ▶ Start the sensorTOOL program.

You can find this program online at <https://www.micro-epsilon.com/fileadmin/download/software/sensorTool.exe>.

- ▶ Select **thermoMETER** from the **Sensor** group drop-down menu and **thermoMETER UC** from the **Sensor type** drop-down menu.

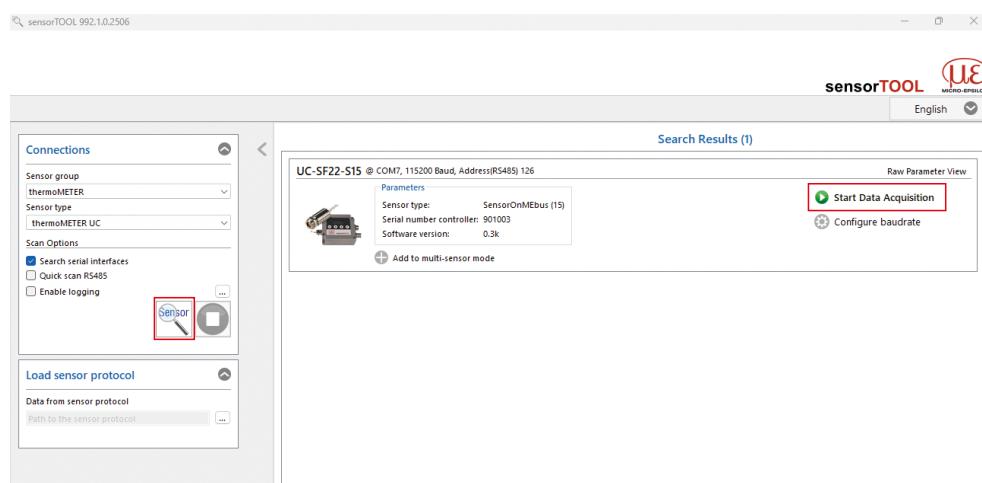


Fig. 8.1: First interactive site after calling the sensorTOOL

- ▶ Check the box **Search serial interfaces**.
- ▶ Click on the **Sensor** button with the magnifying glass icon in order to start the search.

All available channels will now be displayed in the **Search Results (x)** overview.

- ▶ Click on the **Start Data Acquisition** button or the **Sensor** icon to start the measurement.

### 8.2 Measurement menu

#### 8.2.1 General

The recorded data is used to check the measurement. The measurement is influenced by the settings.

The following window appears:

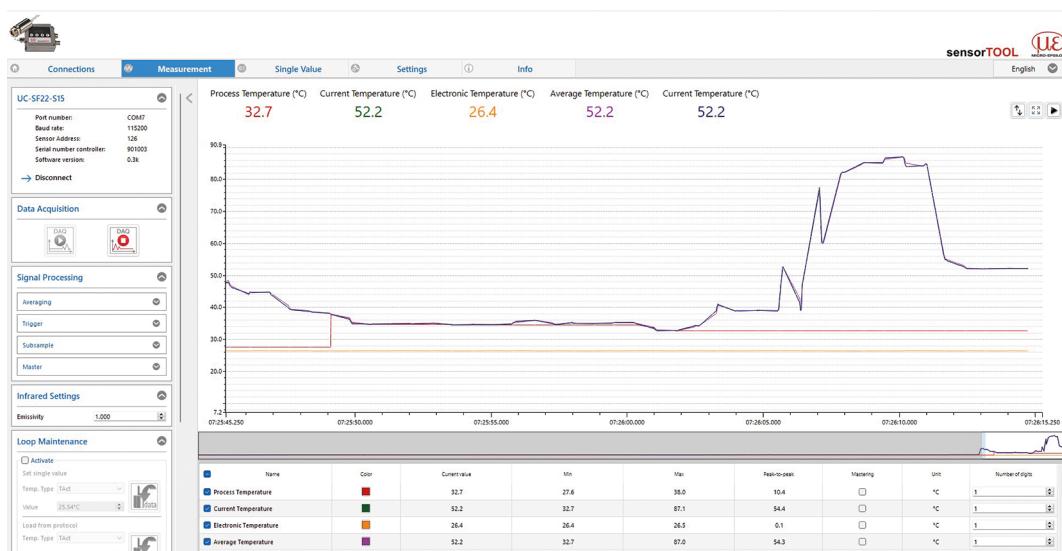


Fig. 8.2: View sensorTOOL thermoMETER UC Measurement menu

- Set your desired settings in the **Settings**, see [Chap. 8.3](#) menu, before recording data for the first time.



Fig. 8.3: Data Acquisition Start / Stop buttons



Recording is restarted when you press this button.  
The previously paused recording is lost.



Recording is stopped when you click this button.

Tab. 8.1: Start / Stop buttons

In the **Signal Processing** menu, you will find the functions for signal processing in the **sensorTOOL** and not in the **sensor**.

In the lower table of the menu you will find various options for showing or hiding:

<b>Name</b>	Signal curves of the sensors used can be hidden and shown.
<b>Color</b>	Change the color settings of the single signal curves.
<b>Current value</b>	Outputs the current measurement value
<b>Min</b>	Minimum measurement value
<b>Max</b>	Maximum measurement value
<b>Peak-to-peak</b>	Difference between Max and Min
<b>Mastering</b>	No function with this sensor series.
<b>Unit</b>	Selection of the output to be displayed. <sup>[11]</sup>
<b>Decimal places</b>	Selection from 0 to 12 possible.

Tab. 8.2: Overview data acquisition

### Ending the measurement

- Once the measurement is complete, press the **Disconnect** button. You can then reconnect using the **sensor search**.

[11] Is set in the menu **Settings** > **General** > **Device Settings** > **Temperature Unit**.

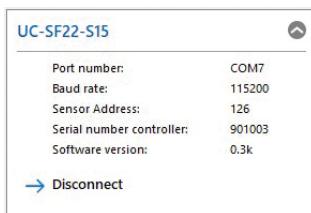


Fig. 8.4: sensorTOOL thermoMETER UC Disconnect

## 8.2.2 Recording and saving measurements

During data acquisition, the measurement data is only displayed and not automatically saved on the PC. In the side menu under CSV Output, you can start transmitting data into a \*.CSV file or only save the currently visible area from the time graph.

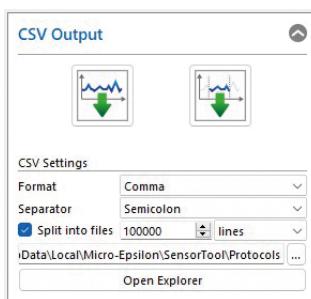


Fig. 8.5: View sensorTOOL CSV Output



Data acquisition into a \*CSV file is started when you press this button.



The recording is saved when you press this button.

Tab. 8.3: Record and save measurement

You can make further settings under Split into files:

CSV Output	CSV Settings	Format	Point / comma
		Separator	Comma / semicolon / tab
		Split data	Value lines / MB / min / hourly / time point / DAQ-Start

With Open Explorer, the previously selected path opens in Explorer, where you can view the recorded measurement results.

## 8.2.3 Infrared settings

In the side menu under Infrared Settings, you can also change the Emissivity set in the Settings > General menu. The adjustment takes place simultaneously in both menus.



Fig. 8.6: View sensorTOOL Infrared Settings

## 8.2.4 Loop maintenance

In the side menu under Loop Maintenance, you can also change the Loop Maintenance set in the menu Settings > Output, see Chap. 8.3.2 and display the values.

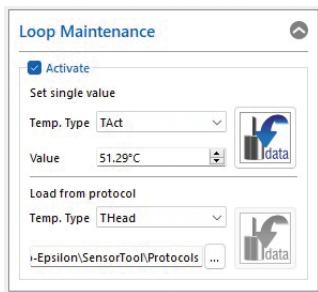


Fig. 8.7: View sensorTOOL Loop Maintenance

Loop Maintenance	Set single value	Temp. Type	TAct / TBox / THead
		Value (single)	Value
	Load from protocol	Temp. Type	TAct / TBox / THead



**Set single value** outputs a single value.



To output a protocol, first select the desired Explorer path. **Load from protocol** loads data from protocol when the second button is clicked.

Tab. 8.4: Set single value and Load from protocol

## 8.2.5 Single value menu

In the Single Value menu, you can enlarge the display of up to 5 measured values.

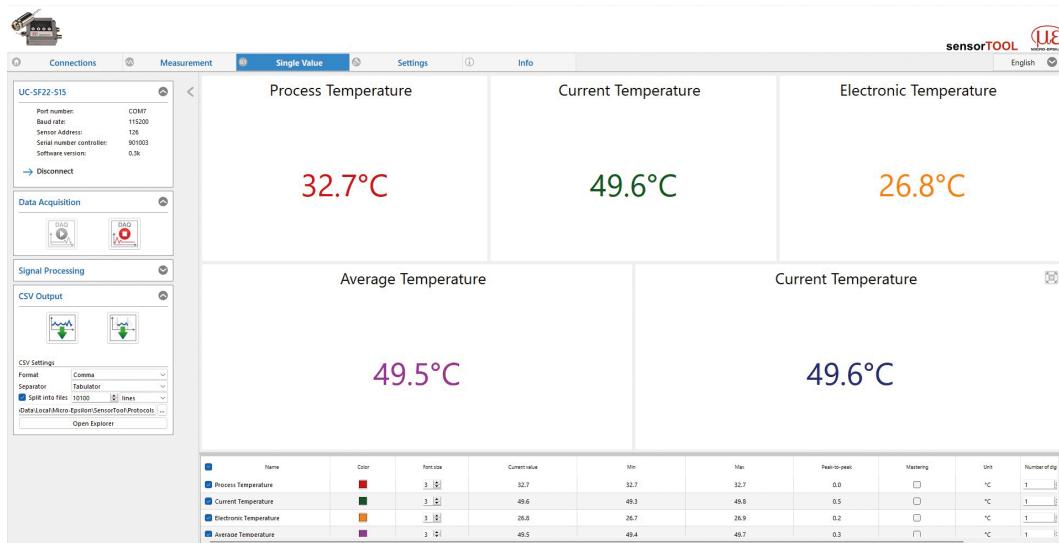


Fig. 8.8: View sensorTOOL thermoMETER UC Single Value

In the lower table of the Single Value menu, you will find various options for showing or hiding the settings you selected in the Settings < Signal Processing, see Chap. 8.3.3 menu. In addition, you can display the values, see Tab. 8.2.

## 8.3 Settings menu

### 8.3.1 Selection menu

- Start the settings by clicking on **Settings** in the menu bar.

There are 4 menus for setting your measured values:

- General

- Signal Processing
- Output
- Alarms and Failsafe

### 8.3.2 General menu

#### 8.3.2.1 Overview

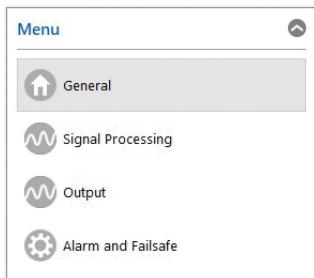


Fig. 8.9: View sensorTOOL - Settings menu - General

#### 8.3.2.2 Device settings

Here you can set the Temperature Unit for the display and data output.

Device Settings	Temperature Unit		°C
	LCD display		°F
	First row	TProc / TAvg / TAct / TBox / THead / Emissivity	

Automatic Switch-Off after an adjustable time (1 min to 10 min) deactivates the LCD backlight until either a button is pressed or an alarm event occurs. The backlight is permanently active if the checkbox is not set.

#### Advanced Settings

Activate Aiming-Laser switches on the power supply for an optional laser sighting.

The Panel-Lock can be used to lock the controller keypad. The settings can then only be displayed, but not changed.

#### 8.3.2.3 Infrared settings

##### Setting the Emissivity and Transmissivity

The Emissivity (epsilon) is a material constant that describes the ability of a body to emit infrared energy.

The Transmissivity or transmittance compensates for the signal loss if a protective window or an additional lens is mounted between the sensor and the measuring object.

Infrared Settings	Emissivity and Transmissivity	Emissivity	Value
		Transmissivity	Value
	Advanced	Ambient Temperature Mode	Automatic
			Fixed Value
		Automatic Emissivity Calculation	Process Temperature

#### Advanced Settings

Depending on the ambient temperature of the sensor head, this can falsify the measurement result. This influence can be compensated for via the Ambient Temperature Mode.

The Ambient Temperature Mode can be selected as follows:

- **Automatic:** The ambient temperature is determined by the temperature probe in the sensor.
- **Fixed Value:** The ambient temperature value is permanently set to the entered value.

### 8.3.3 Signal processing menu

#### 8.3.3.1 Overview

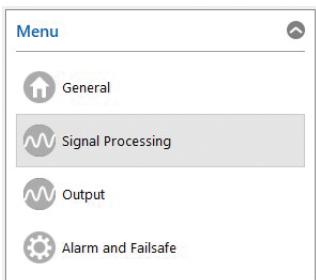


Fig. 8.10: View sensorTOOL - Settings menu - Signal Processing

#### 8.3.3.2 Minimum and maximum hold mode

Activating Hold Mode activates one of the following arithmetic algorithms:

- Minimum Search

In this mode, the sensor waits for rising signals. When the signal rises, the algorithm holds the previous signal level for the specified hold time. The definition of the algorithm corresponds to the maximum search (inverted).

- Maximum Search

In this mode, the sensor waits for descending signals. If the signal drops, the algorithm holds the previous signal peak for the specified hold time.

- Advanced Minimum Search

This mode is the reverse function of the extended maximum search. The sensor waits for local minima. Minimum values that are higher than their predecessors are only adopted if the temperature previously exceeded the threshold value.

If Hysteresis is activated, a minimum value must also increase by the value of the hysteresis before the algorithm accepts the value as the new minimum value.

- Advanced Maximum Search

In this mode, the sensor waits for local peak values.

Peak values that are lower than their predecessors are only accepted if the temperature has fallen below the threshold value.

If Hysteresis is activated, a peak value must also decrease by the value of the hysteresis before the algorithm accepts it as the new peak value.

Minimum Maximum Mode	and Hold	Hold Mode	Disabled			
			Minimum Search		Hold time	minimum search
			Maximum Search		Hold Time	Maximum Search
			Advanced Minimum Search		Hold Time	Minimum Search
					Temperature Threshold	Value
					Temperature Hysteresis	Value
			Advanced Maximum Search		Hold Time Maximum Search	Value
					Temperature Threshold	Value
					Temperature Hysteresis	Value

### 8.3.3.3 Averaging

Depending on the selected function, an arithmetic mean value is calculated with the separately set time constant.

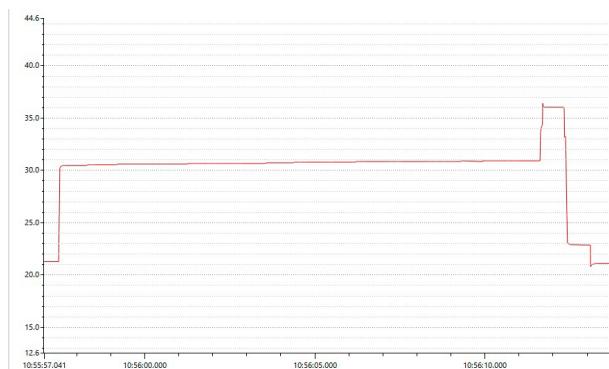
When using the **Normal** mode, an arithmetic mean value is calculated.

An intelligent algorithm is activated when **Hysteresis** mode is used. Rapid temperature rises are passed directly to the signal output if the set averaging hysteresis is exceeded, so that dynamic events can be recorded despite averaging.

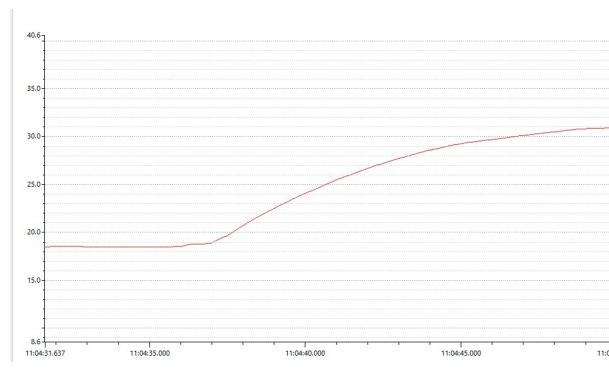
Averaging	<i>Normal</i>	<i>Averaging Time</i>	<i>Value</i>
	<i>Hysteresis</i>	<i>Averaging Time</i>	<i>Value</i>
		<i>Averaging Hysteresis</i>	<i>Value</i>

#### Intelligent averaging with Hysteresis

Averaging is generally used to smooth signal curves. This function can be optimally adapted to the respective application using the adjustable **Averaging Time** parameter. One disadvantage of averaging is that rapid temperature rises caused by dynamic events are subject to the same averaging time and are therefore only available at the signal output with a time delay. The intelligent averaging function (**Hysteresis**) eliminates this disadvantage by passing rapid temperature rises directly to the signal output without averaging.



Signal course with intelligent averaging (Hysteresis)



Signal course without intelligent averaging (Normal)

Tab. 8.5: Signal course with and without intelligent averaging (Hysteresis)

### 8.3.3.4 Function automatic emissivity calculation

With the **Automatic Emissivity Calculation**, the pyrometer can determine an emissivity at a known object temperature. If a **Process Temperature** has been entered, the corresponding emissivity can be determined using the **Calculate** button.

### 8.3.3.5 LED alignment (advanced)

The **LED Alignment** activates the aiming aid function for the sensor.

The sensor can be mechanically aligned using the display backlight.

LED Alignment (Advanced)	Search Mode	<i>Disabled</i>		
		<i>Minimum</i>	<i>Hysteresis</i>	<i>Value</i>
			<i>Reset Time</i>	<i>Value</i>
		<i>Maximum</i>	<i>Hysteresis</i>	<i>Value</i>
			<i>Reset Time</i>	<i>Value</i>

The backlight switches on or off depending on the set function.

### 8.3.3.6 Signal selection (advanced)

The **Signal Selection** determines which and how many temperature values are permanently transmitted to the sensorTOOL.

This selection determines the data displayed in the graphical Measurement tab, [see Chap. 8.2](#), and the Single Value tab. There are 5 different temperature types available for digital output:

Temperature Type	Meaning
TProc	Process temperature = temperature value with signal processing functions
TAvg	Averaged temperature = temperature value with averaging function
TAct	Temperature raw value = temperature value without signal processing functions
TBox	Temperature of the controller
THead	Temperature of the sensor

Tab. 8.6: Temperature types of signal selection

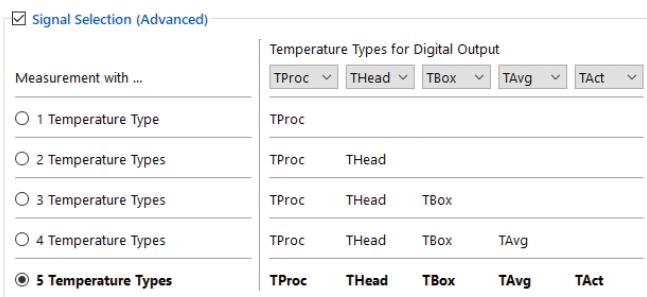


Fig. 8.11: Signal Selection (Advanced) with various options

### 8.3.4 Output menu

#### 8.3.4.1 Overview

The number of transferred temperatures is defined by selecting the corresponding line. The measured value and the order in which the temperature values are output can be defined in the individual line.

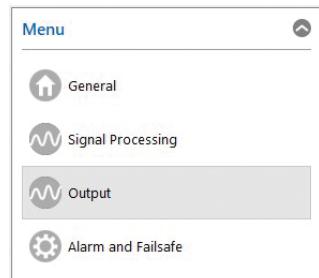


Fig. 8.12: View sensorTOOL - Settings menu - Output

#### 8.3.4.2 Analog output settings

The Output Mode settings enables to activate the analog output Voltage Output or the Current Output.

If Disabled is selected, all available analog outputs are switched off.

Analog Output settings	Output Mode	Disabled			
		Voltage Output / Current Output	Output Minimum Value	Value	Value
Advanced			Temperature for Minimum Output	Value	Value
			Temperature for Maximum Output	Value	Value

The upper and lower limits for the output scaling of the analog output and the upper and lower temperature limits for the scaling are defined via the Advanced entry.

### 8.3.4.3 Loop maintenance (advanced)

Loop Maintenance makes it possible to simulate an output value to check the wiring or scaling of a connected PLC. As long as this mode is activated, the sensor does not output any measured values but only the set simulation values.

Loop Maintenance (Advanced)	Loop Maintenance Status	Disabled		
		Enabled		TAct / TBox / THead
		Temperature Type		Value
		Temperature Value (Digital)		Value
		Temperature Value (Analog)		Value
		Voltage/Current Value (Analog)	Value	Value
		Percentage Value (Analog)		Value

### 8.3.4.4 Calibration (advanced)

Calibration allows the user to specifically adjust the sensor using an offset and gain value, regardless of the factory settings.

Calibration (Advanced)	Tweak Offset	Value in °C
	Tweak Gain	Value

## 8.3.5 Alarm and failsafe menu

### 8.3.5.1 Overview

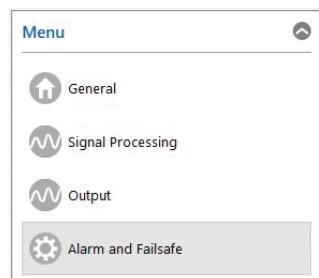


Fig. 8.13: View sensorTOOL - Settings menu - Alarm and Failsafe

### 8.3.5.2 Alarm settings

The **Alarm Source** is used to set the function of the alarm channel.

The other entries are used to define the alarm source (temperature value) for the alarm output. The temperature determines when the alarm is triggered and the alarm relay changes its switching state. **Off** deactivates the alarm output.

Alarm 1 / Alarm 2	Alarm source	TProc / TAvg / TAct / TBox / THead / Differenz / TAct / THead
	Advanced	Activate Alarm
		Normal Open Normal Closed

If you check **Advanced**, you can activate the alarm directly and set the **Alarm Switching Temperature** and the **Alarm Hysteresis**.

### 8.3.5.3 Failsafe settings (advanced)

Failsafe Mode enables to output values at the analog output that lie outside the specified analog scaling, depending on adjustable temperature values via assigned temperature limits. This makes it possible to signal error states via the analog output.

## Failsafe Mode

Failsafe Mode	Disabled			
	Analog Out	Surveillance of	<i>TProc</i>	
			<i>THead</i>	
			<i>TAct</i>	
			<i>TBox</i>	

### Analog Output Failsafe

If Analog Out is selected, the following settings are possible under Analog Output Failsafe:

Analogue Output	Value
Voltage Output for $T < \text{Threshold}$	<i>Value</i>
Voltage Output for $T > \text{Threshold}$	<i>Value</i>
Current Output for $T < \text{Threshold}$	<i>Value</i>
Current Output for $T > \text{Threshold}$	<i>Value</i>

Tab. 8.7: Analog Output Failsafe

Temperature thresholds	<i>Minimum TProc</i>	<i>Value</i>
	<i>Maximum TProc</i>	<i>Value</i>
	<i>Minimum TAct</i>	<i>Value</i>
	<i>Maximum TAct</i>	<i>Value</i>
	<i>Minimum THead</i>	<i>Value</i>
	<i>Maximum THead</i>	<i>Value</i>
	<i>Minimum TBox</i>	<i>Value</i>
	<i>Maximum TBox</i>	<i>Value</i>

Tab. 8.8: Temperature thresholds

## 8.4 Info menu

- Switch to the Info menu.

This view gives you additional information about the connected system. In addition, the settings can be exported or imported, or copied to a clipboard, and the system can be reset to factory settings.



Clicking the Copy to clipboard button copies the information and settings for the selected sensor to the clipboard.



By confirming the Factory settings button, you can restore the factory state. All deactivated channels are reactivated, and the intensity adjustments and special channel-related settings are reset. Confirm the dialog box that opens with Yes to reset the sensor.



Export Settings opens the Explorer and offers to save the sensor settings in a predefined \*.csv file on the PC.



Import Settings opens the Explorer and offers to import the sensor settings from a predefined \*.csv file on the PC.

When you click on the Disconnect button, the menu jumps back to the sensorTOOL start page.

## 8.5 Communication settings

<b>Serial Interface</b>	
Baud rate:	9600, 19200, 38400, 57600, 115200 (standard) <sup>[12]</sup> .
Data bits:	8
Parity:	even
Stop bits:	1
Flow control:	Off

### Protocol

The sensors use the ME bus protocol as standard, which provides the full range of functions. In addition to this protocol, the sensor can also be converted to a simplified binary protocol using the `sensorTOOL` software. In this case, there is no additional overhead in order to achieve fast communication.

[12] Settings in the `sensorTOOL` software

## 9 Cleaning

### Lens cleaning:

Loose particles can be blown away with clean compressed air. The lens surface can be cleaned with a soft, damp cloth (moistened with water) or a lens cleaner (e.g. Zeiss Cleaning Fluid, Edmund Lens Cleaner).

#### NOTICE

Avoid exposure of sensor (both optics and housing) to cleaning agents that contain solvents.

- Damage to or destruction of the sensor

## 10 Principle of infrared temperature measurement

Depending on the temperature, every body emits a certain amount of infrared radiation. A change in the temperature of the object is accompanied by a change in the intensity of the radiation.

The wavelength range of this so-called "thermal radiation" used for infrared measurement technology is between approx. 1  $\mu\text{m}$  and 20  $\mu\text{m}$ . The intensity of the emitted radiation depends on the material.

The material-dependent constant is referred to as emissivity ( $\epsilon$  - epsilon) and is known for most substances, [see Chap. 11.4](#), [see Chap. 11.5](#). Infrared pyrometers are optoelectronic sensors. They detect the infrared radiation emitted by a body and calculate the surface temperature based on this. Probably the most important feature of infrared pyrometers is the non-contact measurement technique, which allows the temperature of difficult-to-access or moving objects to be determined. Infrared pyrometers essentially consist of the following components:

- Lens
- Spectral filter
- Detector
- Controller

The properties of the lens largely determine the beam path of the infrared thermometer, which is characterized by the ratio of distance- to-spot-size. The filter is used to select the wavelength range that is relevant for the temperature measurement. Together with the controller, the detector converts the intensity of the emitted infrared radiation into electrical signals.

## 11 Emissivity

### 11.1 Definition

The intensity of the infrared heat radiation emitted by each body depends on both the temperature and the radiation properties of the material to be examined. The emissivity ( $\epsilon$  - epsilon) is the corresponding material constant that describes the ability of a body to emit infrared energy. It can be between 0% and 100%. An ideally radiating body, a so-called "black body", has an emissivity of 1, while the emissivity of a gold mirror, for example, is  $< 0.1$ .

If the emissivity is set too high, the infrared thermometer determines a lower temperature than the real temperature, provided that the object being measured is warmer than the surroundings. With a low emissivity (reflective surfaces), there is a risk that interfering infrared radiation from background objects (flames, heating systems, fireclay, etc.) will distort the measurement result. To minimize the measurement error in this case, the device should be handled very carefully and shielded from reflective radiation sources.

### 11.2 Determination of an unknown emissivity

- The current temperature of the measuring object can be determined using a thermocouple, contact sensor or similar. The temperature can then be measured with the infrared temperature sensor. The emissivity can be changed until the displayed measurement value matches the actual temperature.
- For temperature measurements up to 380 °C, it is possible to attach a special plastic sticker to the measured object.
  - Set the emissivity to 0.95 and measure the temperature of the sticker.
  - Then determine the temperature of a directly adjacent surface on the measuring object and set the emissivity so that the value corresponds to the previously measured temperature of the plastic sticker.
- Apply matt black paint to part of the surface of the object to be measured.
  - Set the emissivity of your infrared thermometer to 0.98 and measure the temperature of the black-colored surface.
  - Then determine the temperature of a directly adjacent surface and change the emissivity setting until the measured temperature corresponds to that of the colored area.

i With all three methods, the object must have a different temperature from the room temperature.

### 11.3 Characteristic emissivities

If you do not wish to use any of the methods described above to determine your emissivity, you can use guide values from the following emissivity tables.

i Please note that the tables only show average values.

The actual emissivity of a material is influenced by the following factors, among others:

- Temperature
- Measuring angle
- Geometry of the surface (plane, convex, concave)
- Thickness of material
- Structure of the surface (polished, oxidized, rough, sandblasted)
- Spectral range of the measurement
- Transmission properties (e.g. with thin film)

### 11.4 Emissivity table for metals

Material		Typical emissivity			
Spectral sensitivity		1.0 $\mu\text{m}$	1.6 $\mu\text{m}$	5.1 $\mu\text{m}$	8 - 14 $\mu\text{m}$
Aluminum	Not oxidized	0.1 ... 0.2	0.02 ... 0.2	0.02 ... 0.2	0.02 ... 0.1
	Polished	0.1 ... 0.2	0.02 ... 0.1	0.02 ... 0.1	0.02 ... 0.1
	Roughened	0.2 ... 0.8	0.2 ... 0.6	0.1 ... 0.4	0.1 ... 0.3
	Oxidized	0.4	0.4	0.2 ... 0.4	0.2 ... 0.4

Material		Typical emissivity			
Lead	Polished	0.35	0.05 ... 0.2	0.05 ... 0.2	0.05 ... 0.1
	Roughened	0.65	0.6	0.4	0.4
	Oxidized		0.3 ... 0.7	0.2 ... 0.7	0.2 ... 0.6
Chrome		0.4	0.4	0.03 ... 0.3	0.02 ... 0.2
Iron	Not oxidized	0.35	0.1 ... 0.3	0.05 ... 0.25	0.05 ... 0.2
	Rusted		0.6 ... 0.9	0.5 ... 0.8	0.5 ... 0.7
	Oxidized	0.7 ... 0.9	0.5 ... 0.9	0.6 ... 0.9	0.5 ... 0.9
	Forged, blunt	0.9	0.9	0.9	0.9
	Molten	0.35	0.4 ... 0.6		
Iron, cast	Not oxidized	0.35	0.3	0.25	0.2
	Oxidized	0.9	0.7 ... 0.9	0.65 ... 0.95	0.6 ... 0.95
Gold		0.3	0.01 ... 0.1	0.01 ... 0.1	0.01 ... 0.1
Haynes	Alloy	0.5 ... 0.9	0.6 ... 0.9	0.3 ... 0.8	0.3 ... 0.8
Inconel	Electropolished	0.2 ... 0.5	0.25	0.15	0.15
	Sandblasted	0.3 ... 0.4	0.3 ... 0.6	0.3 ... 0.6	0.3 ... 0.6
	Oxidized	0.4 ... 0.9	0.6 ... 0.9	0.6 ... 0.9	0.7 ... 0.95
Copper	Polished	0.05	0.03	0.03	0.03
	Roughened	0.05 ... 0.2	0.05 ... 0.2	0.05 ... 0.15	0.05 ... 0.1
	Oxidized	0.2 ... 0.8	0.2 ... 0.9	0.5 ... 0.8	0.4 ... 0.8
Magnesium		0.3 ... 0.8	0.05 ... 0.3	0.03 ... 0.15	0.02 ... 0.1
Brass	Polished	0.35	0.01 ... 0.5	0.01 ... 0.5	0.01 ... 0.5
	Harshened	0.65	0.4	0.3	0.3
	Oxidized	0.6	0.6	0.5	0.1
Molybdenum	Not oxidized	0.25 ... 0.35	0.1 ... 0.3	0.1 ... 0.15	0.1
		0.5 ... 0.9	0.4 ... 0.9	0.3 ... 0.7	0.2 ... 0.6
Monel (Ni-Cu)		0.3	0.2 ... 0.6	0.1 ... 0.5	0.1 ... 0.14
Nickel	Electrolytic	0.2 ... 0.4	0.1 ... 0.3	0.1 ... 0.15	0.05 ... 0.15
	Oxidized	0.8 ... 0.9	0.4 ... 0.7	0.3 ... 0.6	0.2 ... 0.5
Platinum	Black		0.95	0.9	0.9
Mercury			0.05 ... 0.15	0.05 ... 0.15	0.05 ... 0.15
Silver		0.04	0.02	0.02	0.02
Steel	Polished pitch	0.35	0.25	0.1	0.1
	Stainless	0.35	0.2 ... 0.9	0.15 ... 0.8	0.1 ... 0.8
	Heavy plates			0.5 ... 0.7	0.4 ... 0.6
	Cold-milled	0.8 ... 0.9	0.8 ... 0.9	0.8 ... 0.9	0.8 ... 0.9
	Oxidized	0.8 ... 0.9	0.8 ... 0.9	0.7 ... 0.9	0.7 ... 0.9
Titanium	Polished	0.5 ... 0.75	0.3 ... 0.5	0.1 ... 0.3	0.05 ... 0.2
	Oxidized		0.6 ... 0.8	0.5 ... 0.7	0.5 ... 0.6
Tungsten	Polished	0.35 ... 0.4	0.1 ... 0.3	0.05 ... 0.25	0.03 ... 0.1
Zinc	Polished	0.5	0.05	0.03	0.02
	Oxidized	0.6	0.15	0.1	0.1
Tin	Not oxidized	0.25	0.1 ... 0.3	0.05	0.05

## 11.5 Emissivity table for non-metals

Material		Typical emissivity			
Spectral sensitivity		1.0 µm	2.3 µm	5.1 µm	8 - 14 µm
Asbestos		0.9	0.8	0.9	0.95
Asphalt				0.95	0.95
Basalt				0.7	0.7
Concrete		0.65	0.9	0.9	0.95
Ice					0.98
Soil					0.9 ... 0.98
Color	Not alkaline				0.9 ... 0.98
Gypsum				0.4 ... 0.97	0.8 ... 0.95
Glass	Washer		0.2	0.98	0.85
	Melting material		0.4 ... 0.9	0.9	
Rubber				0.9	0.95
Wood	Natural			0.9 ... 0.95	0.9 ... 0.95
Limestone				0.4 ... 0.98	0.98
Carborundum			0.95	0.9	0.9
Ceramics		0.4	0.8 ... 0.95	0.8 ... 0.95	0.95
Gravel				0.95	0.95
Carbon	Not oxidized		0.8 ... 0.9	0.8 ... 0.9	0.8 ... 0.9
	Graphite		0.8 ... 0.9	0.7 ... 0.9	0.7 ... 0.9
Plastics > 50 µm	Opaque			0.95	0.95
Paper	Any color			0.95	0.95
Sand				0.9	0.9
Snow					0.9
Textiles				0.95	0.95
Water					0.93

## 12 Disclaimer

All components of the device have been checked and tested for functionality in the factory. However, should any defects occur despite careful quality control, these shall be reported immediately to Micro-Epsilon or to your distributor / retailer.

Micro-Epsilon undertakes no liability whatsoever for damage, loss or costs caused by or related in any way to the product, in particular consequential damage, e.g., due to

- non-observance of these instructions/this manual,
- improper use or improper handling (in particular due to improper installation, commissioning, operation and maintenance) of the product,
- repairs or modifications by third parties,
- the use of force or other handling by unqualified persons.

This limitation of liability also applies to defects resulting from normal wear and tear (e.g., to wearing parts) and in the event of non-compliance with the specified maintenance intervals (if applicable).

Micro-Epsilon is exclusively responsible for repairs. It is not permitted to make unauthorized structural and / or technical modifications or alterations to the product. In the interest of further development, Micro-Epsilon reserves the right to modify the design or the firmware.

In addition, the General Terms of Business of Micro-Epsilon shall apply, which can be accessed under Legal details | Micro-Epsilon <https://www.micro-epsilon.com/legal-details/>.

## 13 Service, repair

If the measuring system is defect, please send in the affected parts for repair or replacement.

If the cause of a fault cannot be clearly identified, please send the entire system including cables to:

MICRO-EPSILON MESSTECHNIK  
GmbH & Co. KG  
Koenigbacher Str. 15  
94496 Ortenburg / Germany

Tel: +49 (0) 8542 / 168-0  
Fax: +49 (0) 8542 / 168-90  
[info@micro-epsilon.com](mailto:info@micro-epsilon.com)  
[www.micro-epsilon.com/contact/worldwide/](http://www.micro-epsilon.com/contact/worldwide/)  
<https://www.micro-epsilon.com>

## 14 Decommissioning, disposal

In order to avoid the release of environmentally harmful substances and to ensure the reuse of valuable raw materials, we draw your attention to the following regulations and obligations:

- Remove all cables from the sensor and/or controller.
- Dispose of the sensor and/or the controller, its components and accessories, as well as the packaging materials in compliance with the applicable country-specific waste treatment and disposal regulations of the region of use.
- You are obliged to comply with all relevant national laws and regulations.

For Germany / the EU, the following (disposal) instructions apply in particular:

- Waste equipment marked with a crossed garbage can must not be disposed of with normal industrial waste (e.g. residual waste can or the yellow recycling bin) and must be disposed of separately. This avoids hazards to the environment due to incorrect disposal and ensures proper recycling of the old appliances. 
- A list of national laws and contacts in the EU member states can be found at [https://ec.europa.eu/environment/topics/waste-and-recycling/waste-electrical-and-electronic-equipment-weee\\_en](https://ec.europa.eu/environment/topics/waste-and-recycling/waste-electrical-and-electronic-equipment-weee_en). Here you can inform yourself about the respective national collection and return points.
- Old devices can also be returned for disposal to Micro-Epsilon at the address given in the legal details at <https://www.micro-epsilon.com/legal-details>.
- We would like to point out that you are responsible for deleting the measurement-specific and personal data on the old devices to be disposed of.
- Under the registration number WEEE-Reg.-Nr. DE28605721, we are registered at the foundation Elektro-Altgeräte Register, Nordostpark 72, 90411 Nuremberg, as a manufacturer of electrical and/or electronic equipment.

## 15 Optional accessories

### 15.1 Mounting accessories

TM-MF-UC	Mounting fork	2970751
TM-FB	Mounting bracket	2970753
TM-AB-UC	Mounting bracket, adjustable in 2 axes	2970754
TM-MB-UC	Mounting bolt with M12x1 thread and nut	2970755
TM-TA	Pipe adapter	2970756
TM-T40	Reflection protection tube, length 40 mm; M12x1 external thread	2970757
TM-T88	Reflection protection tube, length 88 mm; M12x1 external thread	2970758
TM-T20	Reflection protection tube, length 20 mm; M12x1 external thread	2970759
TM-MH-UC	Massive housing made from stainless steel	2970760
TM-FBMH-UC	Mounting bracket for solid housing	2970761
TM-CF	Close Focus lens	2970763
TM-PW	Protective window	2970764
TM-MI	Right angle mirror	2970769
TM-DIN-UC	Rail mount adapter	2970750

The controller can be mounted on a DIN rail in accordance with EN50022 (TS35) using the rail mount adapter.

### 15.2 Air purge units

#### NOTICE

Avoid both deposit (dust, particles) and smoke, steam and high air humidity (condensation) on the lens.  
 ▶ Erroneous measurements

These effects are avoided or reduced by using an air purge collar.

**i** Make sure you use oil-free, technically clean air.

The required air volume (approx. 2 ... 10 l/min.) depends on the application and the conditions at the installation site.

TM-AP	Air purge collar	2970767
TM-APL	Air purge collar with laminar air flow and air outlet offset by 90° to the measuring object	2970752
TM-AP8	Air purge collar with 8 mm hose connection	2970768
TM-APMH-UC	Air purge collar made from stainless steel for solid housing	2970762
TM-AP-UC	Air purge collar (stainless steel) for lenses from D/S 15:1	2970765

TM-AP2-UC	Air purge collar (stainless steel) for lenses with D/S 2:1	2970766
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There is an air outlet on the side of the laminar air purge collar. This prevents the measuring object from cooling down at small measuring distances.

### 15.3 Protective window

A protective window is available to protect the sensor lens. It has the same mechanical dimensions as the CF lens and is available in the following variants:

When using the protective window (average values), the following transmission values must be set as a guide value:

Model	Transmissivity
SF15	0.83

*Tab. 15.1: Protective window model and transmission values*

The optionally available USB adapter is required to change the transmission value.

### 15.4 CF ancillary lens

The CF ancillary lens enables the measurement of tiny objects. The minimum measurement spot depends on the sensor used.

The distance is measured from the front edge of the CF lens holder. The ancillary lens is mounted by screwing it on the sensor up to the stop. If the solid housing is used, insert the CF ancillary lens using the the M12x1 external thread.

When using the CF ancillary lens (average values), the following transmission values must be set as a guide value:

Model	Transmittance
SF15	0.85

*Tab. 15.2: Model ancillary lens and transmission values*

### 15.5 Connection cable

TM-PC5/1-M12	Analog signal and supply cable 1 m	2904051
TM-PC5/5-M12	Analog signal and supply cable 5 m	2904052
TM-USBA-M12	Digital signal cable with USB adapter, 1.8 m, M12 plug, USB A plug	2904053
TM-DC8/1-M12	Digital signal cable, 1 m, M12 plug, ferrules, pre-assembled	2904054
TM-DC8/5-M12	Digital signal cable, 5 m, M12 plug, ferrules, pre-assembled	2904055

### 15.6 USB adapter

If the TM-USBA-M12 cable is not used, a TM-DC8/1-M12 or TM-DC8/5-M12 cable can be used in conjunction with the TM-USBA to connect the sensor to a PC.

TM-USBA	USB adapter with terminal block	2970770
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## 16 Factory settings

The sensors have the following default settings on delivery:

Signal output temperature	0 ... 5 V
Emissivity	0.95
Transmittance	1.000
Averaging (AVG)	0.2 s
Smart averaging	Active
Maximum value hold (MAX)	Disabled
Minimum value hold (MIN)	Inactive
Lower limit Output	0 V
Upper limit Output	SF22: 0 ... 9 V (at 0 ... 900 °C) SF02, SF15: 0 ... 6 V (at 0 ... 600 °C)
Temperature unit	°C
Ambient temperature compensation	Internal sensor temperature probe
Baud rate [kBaud]	115200
Lower limit temperature range [°C]	0
Upper limit temperature range [°C]	SF22: 0 ... 9 V (at 0 ... 900 °C) SF02, SF15: 0 ... 6 V (at 0 ... 600 °C)

The factory settings can be changed using the optional USB adapter and the `sensorTOOL`.

Smart Averaging or Adaptive Averaging is a dynamic adaptation of the averaging to steep signal edges. Activation/deactivation is only possible via software.

- If you want to reset to the factory settings using the programming keys, refer to the chapter Resetting to factory settings, [see Chap. 7.3](#).





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